



Mobile Vehicle Security Bus

By: SD MAY 23-14



Presentation Outline

- Intro / Background
- Implementation
- Accomplishments
- Key Contributions
- Challenges + Solutions
- Future Work
- Conclusion
- Live Demonstration

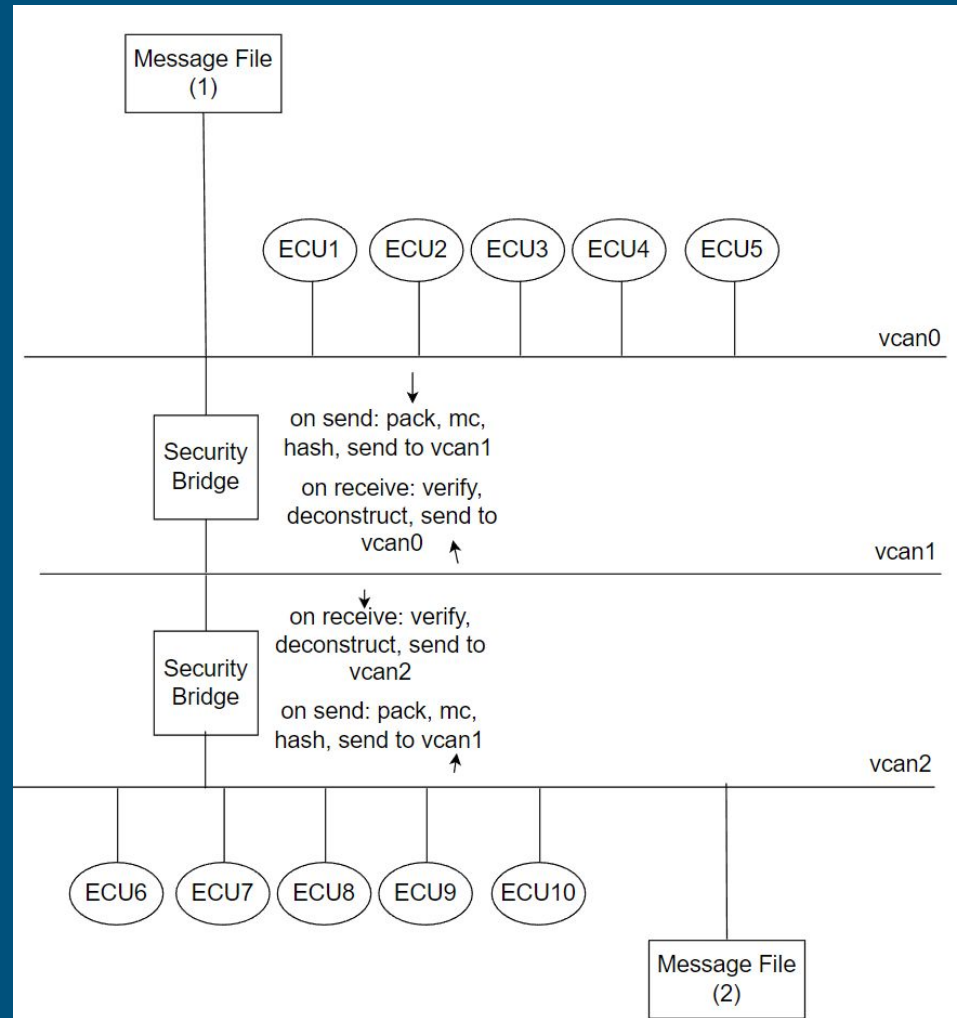
Introduction

- Jeep Hack 2015 (Chrysler UConnect App)
 - Public stunt between journalist + two researchers
 - Root access on car and CAN bus (ECU communications)
 - “Hey Chrysler, please fix this.”
- Fix?
 - Kind of...
 - DIY software download to USB *or*
 - Bring to dealership



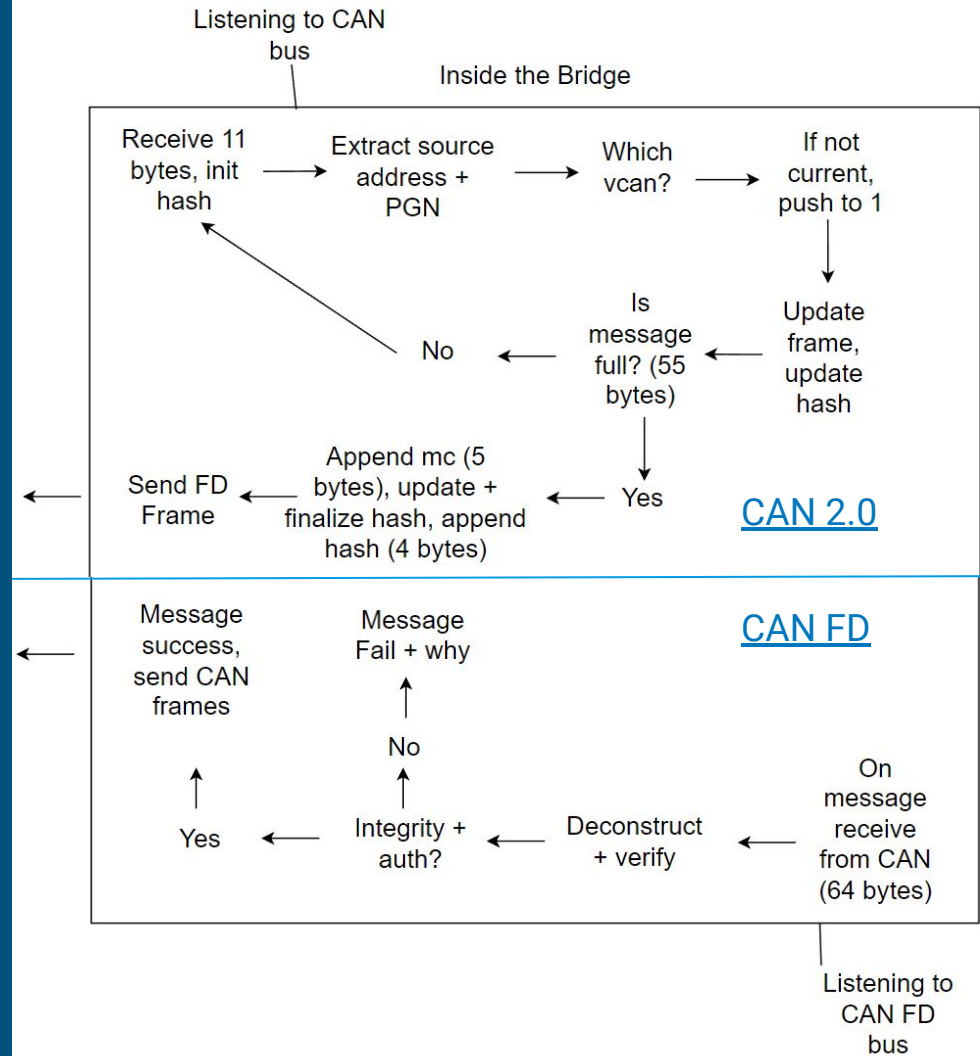
General Architecture

- Message Files
- ECUs
- Virtual Can Buses (vcanX)
- Bridge



Bridge Architecture

- Listening Can Bus
 - Extract fields
 - Determine destination
 - Pack + Hash
 - Is full?
 - If yes, add mc, hash, send
 - If no, continue listening
- Listening FD Bus
 - Deconstruct, verify
 - Security functions
 - If yes, send messages
 - If no, fail + reason



Building CAN FD Frames

CAN Frame 1	Timestamp: 1682784133.434768	ID: 001e001e	X
	DLC: 8	00 40 00 00 00 00 00 00	Channel: vcan0
2	Timestamp: 1682784133.455083	ID: 0006ef00	X
	DLC: 8	64 15 17 f0 c6 23 d8 21	Channel: vcan0
3	Timestamp: 1682784133.455260	ID: 0006ef00	X
	DLC: 8	64 15 17 f0 c6 23 d8 21	Channel: vcan0
4	Timestamp: 1682784133.475654	ID: 0006ef00	X
	DLC: 8	64 15 18 f0 c6 23 d8 21	Channel: vcan0
5	Timestamp: 1682784133.475811	ID: 0006ef00	X
	DLC: 8	64 15 18 f0 c6 23 d8 21	Channel: vcan0
CAN FD Frame	Timestamp: 0.000000	ID: 00abc123	X F
	DLC: 64	1e 00 1e 00 40 00 00 00 00 00 00 00 06 ef 00 64	
		15 17 f0 c6 23 d8 21 06 ef 00 64 15 17 f0 c6 23 d8 21 06 e	
		f 00 64 15 18 f0 c6 23 d8 21 06 ef 00 64 15 18 f0 c6 23 d8	
		21 08 08 83 4d 00 00 00 00 c9	

Accepting / Rejecting Messages

```

Message Accepted:   Timestamp: 1682784131.510908   ID: 00abc123   X   F
    DLC: 64   06 ef 00 64 15 1f f0 3f 24 d8 21 06 ef 00 64 15 10 f0 2c 24 d8 21 0
6 ef 00 64 15 10 f0 2c 24 d8 21 1e 00 1e 00 40 00 00 00 00 00 00 13 ef f0 64 19 81
ff ff ff ff 00 34 b2 c1 a1 00 00 00 00 a1   Channel: vcan1 ✓
Message Fails Counter check:   Timestamp: 1682784131.510921   ID: 00abc123   X
    F   DLC: 64   06 ef 00 64 15 1f f0 3f 24 d8 21 06 ef 00 64 15 10 f0 2c
24 d8 21 06 ef 00 64 15 10 f0 2c 24 d8 21 1e 00 1e 00 40 00 00 00 00 00 00 13 ef
f0 64 19 81 ff ff ff ff 00 34 b2 c1 a1 00 00 00 00 a1   Channel: vcan1 ✗
Message Fails CMAC check:   Timestamp: 1682784131.545252   ID: 00abc123   X
    F   DLC: 64   06 ef 00 64 15 11 f0 2c 24 d8 21 03 f0 05 84 ff ff ff ff ff
ff ff 06 ef 00 64 15 12 f0 13 24 d8 21 06 ef 00 64 15 12 f0 13 24 d8 21 1e 00 1e
00 40 00 00 00 00 00 00 00 f8 f8 d6 42 00 00 00 00 a2   Channel: vcan1 ✗
Message Fails Both Counter and CMAC:   Timestamp: 1682784131.545336   ID: 00abc1
23   X   F   DLC: 64   06 ef 00 64 15 11 f0 2c 24 d8 21 03 f0 05 84 ff
ff ff ff ff ff ff 06 ef 00 64 15 12 f0 13 24 d8 21 06 ef 00 64 15 12 f0 13 24 d8 2
1 1e 00 1e 00 40 00 00 00 00 00 00 f8 f8 d6 42 00 00 00 00 a2 ✗ Channel: vcan1

```


Work Accomplishments

- Messages read from file and packed into 64 byte frames.
- Messages sent across multiple CAN busses.
- CMAC and counter validation, harmful or unexpected messages are rejected
- Message routing based on PGN value to reach desired destination.
- Bidirectionality for proper message control.

Key Contributions

Ryan S

- Packing/unpacking CAN FD frames, sending/receiving frames, validating FD frames, timestamp delays

Ryan C

- AES CMAC, Monotonic Counter, Bidirectionality

Cody

- Sending frames, testing tools, git and codebase organization, example ECU design

Levi

- SocketCAN setup, simulated data flow, helped with sending/unpacking of FD frames

Key Contributions

Josue

- Helped develop ideas and prototype for packing CAN frames, Implemented a routing algorithm, and brainstormed ideas for getting full duplex communication between bridges

Drake

- ECU, Helping Pack/Unpack CAN FD Frames, Routing, Bidirectionality

Riley

- Contributed to the ECU, helped research SocketCAN, Send/Receive/Pack CAN FD Frames, CMAC Debugging, Bidirectionality

Challenges & Solutions

- New concepts for all of us
- Only 1 Cybersecurity Engineering major
- C had minimal documentation for SocketCAN
- Switched to Python at 4 weeks into this semester
- Communicating with a large group

Future Work

- Encryption (to provide confidentiality)
- Expanding the number of Bridges + ECUs in the CAN network
- Physical testing on real hardware + vehicle
- Physical live demo

Conclusion

- A solution for vehicle security is possible
 - Of continued importance as CAN will likely be used in vehicles for many years
 - Current and older vehicles can benefit as well
 - Our approach is theoretically backwards compatible with the older CAN standard

- There's still a lot of work to be done
 - Implementing security mechanisms are challenging due to CAN's limitations
 - Vehicle manufacturers would need to update their vehicles and manufacturing processes