Mobile Vehicle Security Bus

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Presentation Outline

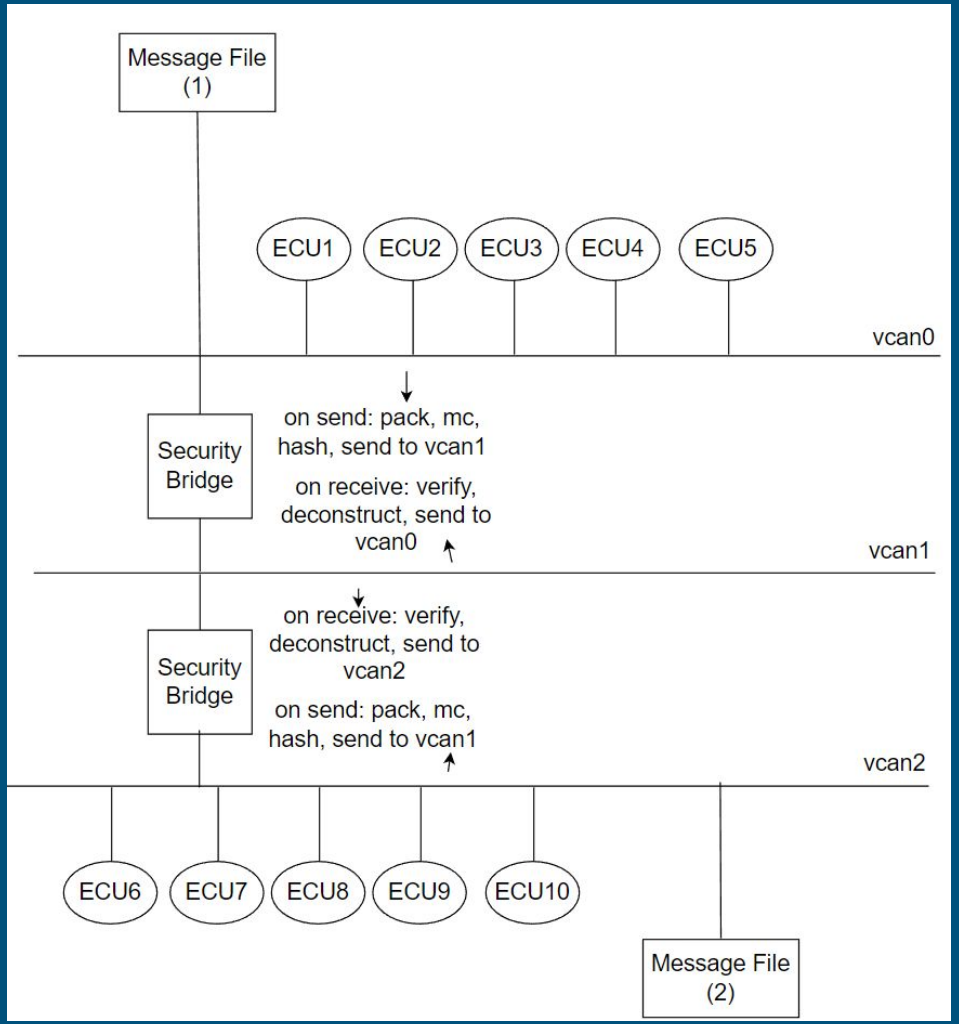
- Intro / Background
- Implementation
- Accomplishments
- Key Contributions
- Challenges + Solutions
- Future Work
- Conclusion
- Live Demonstration

Introduction

- Jeep Hack 2015 (Chrysler UConnect App)
  - Public stunt between journalist + two researchers
  - Root access on car and CAN bus (ECU communications)
  - “Hey Chrysler, please fix this.”
- Fix?
  - Kind of…
    - DIY software download to USB ***or***
    - Bring to dealership

General Architecture

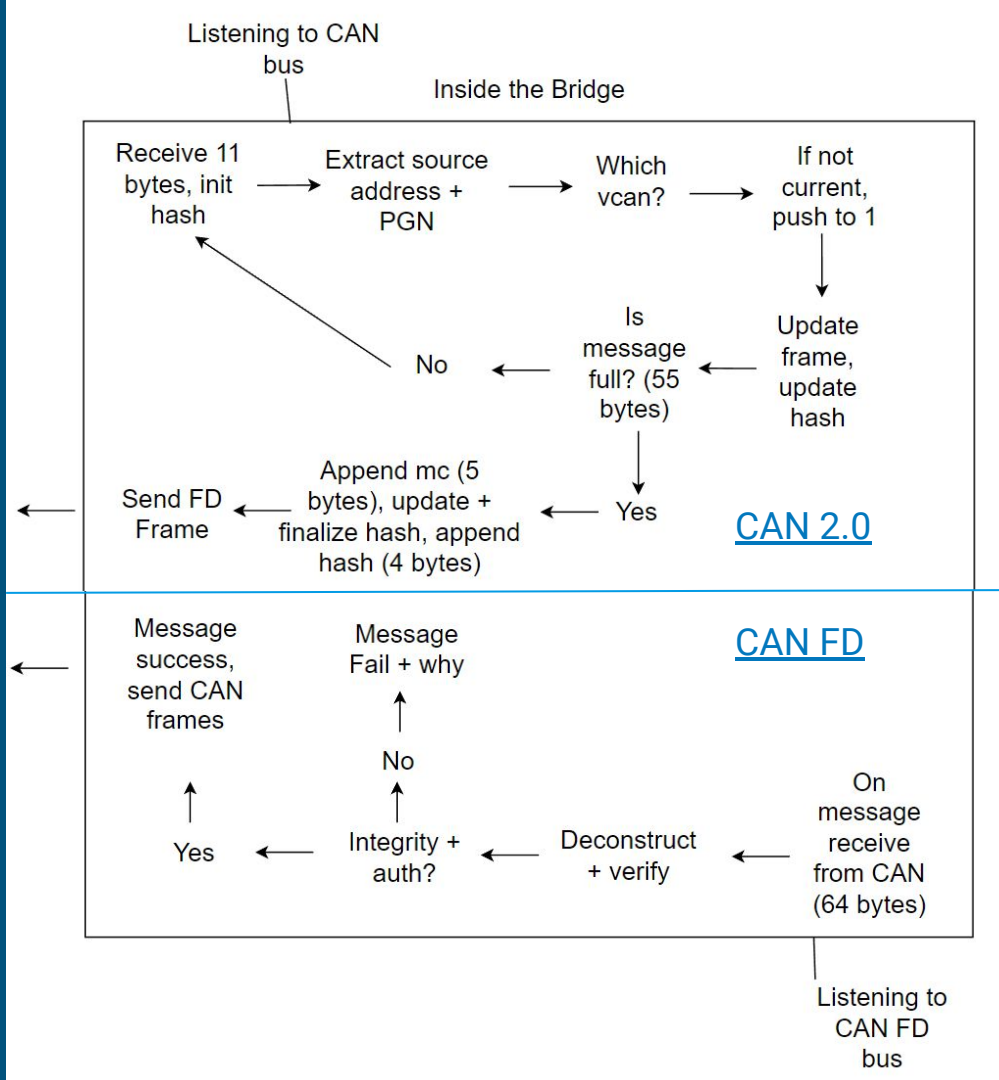
- Message Files
- ECUs
- Virtual Can Buses (vcanX)
- Bridge



Bridge Architecture

- Listening Can Bus
  - Extract fields
  - Determine destination
  - Pack + Hash
  - Is full?
    - If yes, add mc, hash, send
    - If no, continue listening

- Listening FD Bus
  - Deconstruct, verify
  - Security functions
    - If yes, send messages
    - If no, fail + reason



Building CAN FD Frames

CAN Frame 1

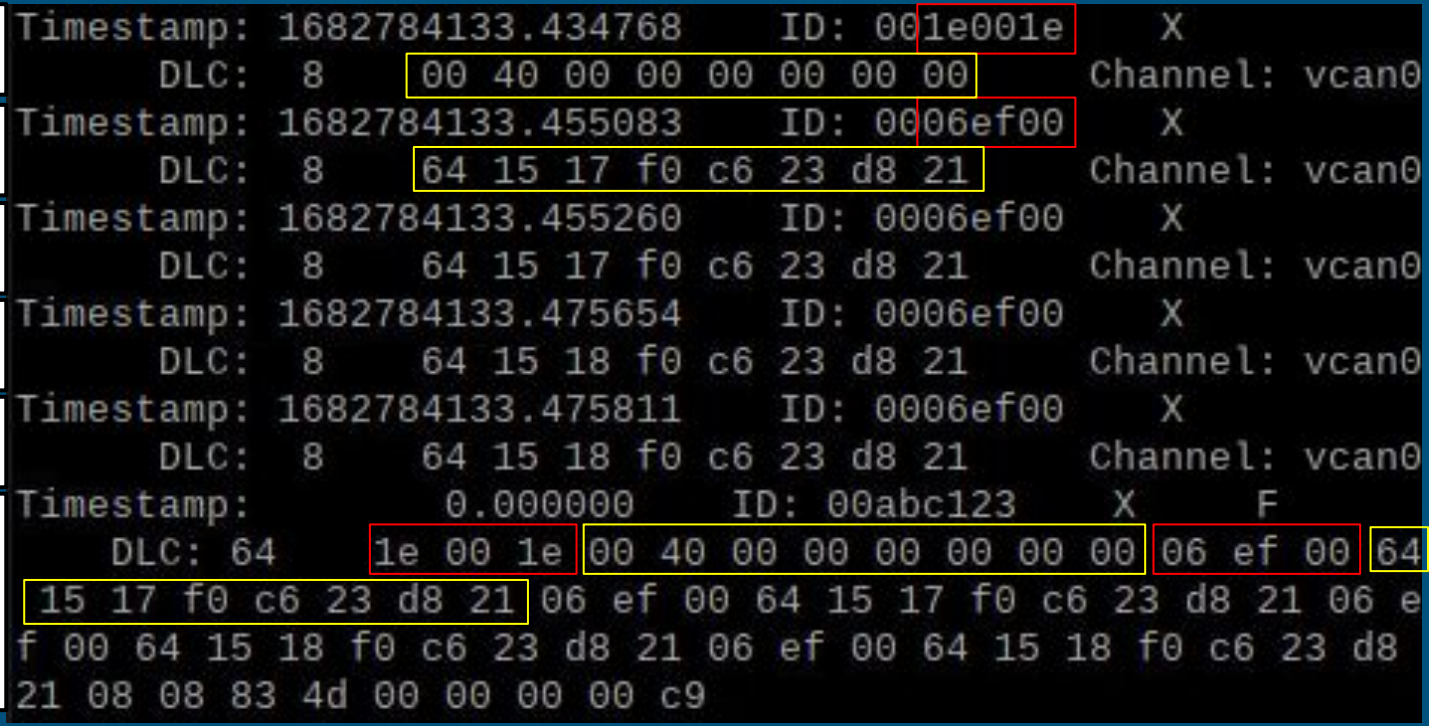
2

3

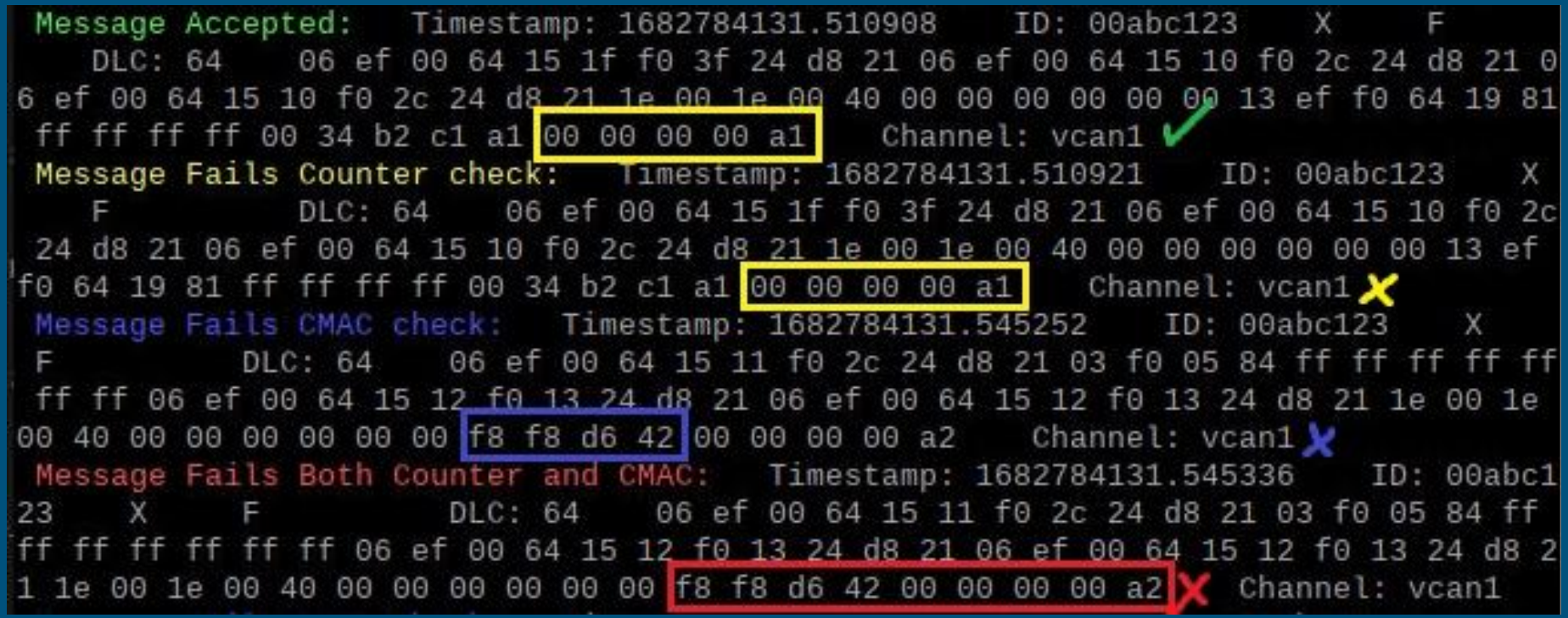
4

5

CAN FD Frame



Accepting / Rejecting Messages



Work Accomplishments

- Messages read from file and packed into 64 byte frames.
- Messages sent across multiple CAN busses.
- CMAC and counter validation, harmful or unexpected messages are rejected
- Message routing based on PGN value to reach desired destination.
- Bidirectionality for proper message control.

Key Contributions

Ryan S

- Packing/unpacking CAN FD frames, sending/receiving frames, validating FD frames, timestamp delays

Ryan C

- AES CMAC, Monotonic Counter, Bidirectionality

Cody

- Sending frames, testing tools, git and codebase organization, example ECU design

Levi

- SocketCAN setup, simulated data flow, helped with sending/unpacking of FD frames

Key Contributions

Josue

- Helped develop ideas and prototype for packing CAN frames, Implemented a routing algorithm, and brainstormed ideas for getting full duplex communication between bridges

Drake

- ECU, Helping Pack/Unpack CAN FD Frames, Routing, Bidirectionality

Riley

- Contributed to the ECU, helped research SocketCAN, Send/Receive/Pack CAN FD Frames, CMAC Debugging, Bidirectionality

Challenges & Solutions

- New concepts for all of us
- Only 1 Cybersecurity Engineering major
- C had minimal documentation for SocketCAN
- Switched to Python at 4 weeks into this semester
- Communicating with a large group

Future Work

- Encryption (to provide confidentiality)
- Expanding the number of Bridges + ECUs in the CAN network
- Physical testing on real hardware + vehicle
- Physical live demo

Conclusion

- A solution for vehicle security is possible
  - Of continued importance as CAN will likely be used in vehicles for many years
  - Current and older vehicles can benefit as well
    - Our approach is theoretically backwards compatible with the older CAN standard

- There’s still a lot of work to be done
  - Implementing security mechanisms are challenging due to CAN’s limitations
  - Vehicle manufacturers would need to update their vehicles and manufacturing processes